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SENSITIVITY ANALYSIS AND GLOBAL ATTRACTIVITY OF THE

HPA AXIS IN A DEPRESSION MODEL

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Abstract: In this paper, we present mathematical model of depression that related hypothalamic-pituitary-adrenal (HPA) axis. HPA axis is an endocrine responsible for stress management that effects from changing level of hormones in HPA axis. Stress management affects the function of the HPA axis causing abnormal hormone secretion, which results in a tendency to depression. Dynamic of depression model is proposed by analysing positive and bounded solutions, existence of equilibria, local stability and sensitivity analysis of equilibrium point. Results of sensitivity analysis can determine which parameters have the most effect on the behaviour of the system. We also analyse global attractivity for impulsive behaviour of the HPA axis model. Moreover, some numerical results of these models may be more inspiring to treat patients more thoroughly and help to diagnose specific patients for low level of risk for depression.

Keywords: Depression; HPA axis; Mathematical modelling; Sensitivity analysis; Global attractivity;

I. INTRODUCTION

Feeling down from time to time is a normal part of life, but when emotions such as hopelessness and despair take hold and just won't go away, you may have depression. More than just sadness in response to life's struggles and setbacks, depression changes how you think, feel, and function in daily activities [1]. Depression is a mental disorder characterized fundamentally by depressive mood, loss of interest, and enjoyment of the positive aspects of life and fatigue, which impoverish the quality of life and generate difficulties in the family, work, and social environment of those who suffer it. Depression can manifest itself regardless of age, gender or socio-economic status. More than 350 million people in the world suffer from depression, and this can become a serious health problem, especially when it is of long duration and moderate to severe intensity, and can cause great suffering and disrupt work, school, family, economic, and emotional activities, among others. However, you experience depression, left untreated it can become a serious health condition. In the worst case, it can lead to suicide, which is the cause of approximately 1 million deaths annually [2].According to

the World Health Organization (WHO) 1 in 20 of the world's population are currently suffering from the disease and patients' chance to become ill with repeated depression 50-70%, the cause is that the teenage suicide is higher. Some illnesses have a specific medical cause, making treatment straightforward, depression is far more complicated. In addition, severely different biological, psychological and social factors also contribute to the risk of depression [1]. Depression is a mental disease diagnosed by psychiatrists. Such diagnoses are based on patient interviews and symptoms with uncertainties as high as 30% as a consequence. In 2011, Vinther et al. [3] studied the modeling of the Hypothalamic-Pituitary-Adrenal (HPA) axis using an analytical and numerical approach, combined with biological knowledge regarding physiological mechanisms and parameters. In 2013, Andersen et al. [4] developed new HPA models resulting in more accurate by taking into account saturation concentration. In 2014, Hoeyer et al. [5] have been studying depression which is associated with malfunctions in HPA axis, the endocrine system of glands and their synthesized hormones. Later in 2017, Bangsgaard et al. [6] have developed a model of the HPA axis by mainly three hormones are CRH, ACTH and Cortisol. CRH is secreted in the hypothalamus where it is transported to the anterior pituitary then stimulates the synthesis of ACTH from the pituitary gland and ACTH stimulates the synthesis of the stress hormone cortisol. Cortisol has an impact on the whole body and especially feeds back by inhibit the secretion of CRH and ACTH from the respective glands. In this work, we develop the HPA axis model [6] with/without impulse and analyse dynamics and behaviors of three hormones as the following diagram.

Fig. 1. The diagram of depression model

The HPA axis can be classify three hormones of CRH (x_1) ,

ACTH
$$
(x_2)
$$
 and cortisol (x_3) as the following:
\n
$$
\frac{dx_1}{dt} = a_0 + C \frac{a_1}{(1 + a_2 x_3^2)} \frac{x_1}{(\mu + x_1)} - \omega_1 x_1,
$$
\n(1)

$$
\frac{dx_2}{dt} = \frac{a_3 x_1}{1 + a_4 x_3} - \omega_2 x_2,\tag{2}
$$

$$
\frac{dx_3}{dt} = a_5 x_2^2 - \omega_3 x_3,\tag{3}
$$

where initial conditions $x_1(0) = c_1 > 0, x_2(0) = c_2 > 0$, $x_3(0) = c_3 > 0$ and all parameters are positive. The interpretation of parameter meanings for the model is shown in the following Table 1.

Table-I:The meaning of parameters for depression model [6]

II. POSITIVE AND BOUNDED SOLUTIONS OF THE MODEL First, we show that the levels of three hormones in the HPA axis model are non-negative as following lemma. **Lemma 1***All levels of three hormones of Eqs.(1)-(3)with any positive initial conditions are non-negative for all t*…0 *.*

Proof:Consider a solution $(x_1(t), x_2(t), x_3(t))$ of Eqs.(1)-(3)with the positive initial conditions. Assuming that there exists a $t_1 > 0$ such that $x_1(t_1) = 0$ and $dx_1(t_1) / dt_2$, 0.

The equation (1)implies that

$$
\frac{dx_1(t_1)}{dt}=a_0>0,
$$

which contradicts with $dx_1(t_1) / dt$, 0, so $x_1(t) > 0$ for all $t > 0$.

Next, the solution of Eq.(3) is gives

$$
x_3(t) = x_3(0)e^{-w_3t} + a_5e^{-w_3t} \frac{1}{2}(s)e^{w_3s} ds > 0,
$$

 $\int \cos x_3(t) > 0$ for all $t > 0$.

Lastly, the solution of Eq.(2), we have
\n
$$
x_2(t) = x_2(0)e^{-w_2t} + a_3e^{-w_2t} \mathbf{O}_0 \underbrace{\overset{t}{\mathbf{E}}}_{\mathbf{E}} + \underbrace{x_1(s)}_{a_4x_3(s)} \underbrace{\overset{\ddot{\mathbf{O}}}{\mathbf{E}}}_{\mathbf{B}}^{w_2s} ds
$$

So, $x_2(t)$ > 0 for all $t > 0$. This proof is complete. W **Lemma 2** *All hormone levels in the HPA axis model (1)-(3) with any positive initial conditions are bounded.* Proof: From, Eq.(1), we have

$$
\frac{dx_1}{dt} = a_0 + C \frac{a_1}{1 + a_2 x_3^2} \frac{x_1}{m + x_1} - w_1 x_1,
$$

$$
w_1(x_1) - w_1 x_1.
$$

therefore

$$
x_1(t),\quad \underset{\mathbf{w}_1}{\overset{\mathbf{R}}{\mathbf{G}}\mathbf{G}_0 + a_1 \frac{\ddot{\mathbf{G}}}{\frac{1}{\dot{\mathbf{G}}}} \quad \underset{\mathbf{w}_1}{\overset{\mathbf{R}}{\mathbf{G}}} \quad \underset{\mathbf{w}_1}{\overset{\mathbf{K}}{\mathbf{G}}} \quad w_1}{\overset{\mathbf{R}}{\mathbf{G}}} + a_1 + x_1(0) \frac{\ddot{\mathbf{G}}}{\frac{1}{\dot{\mathbf{G}}}} \quad w_1^t,
$$
\n
$$
y_1, \quad \underset{\mathbf{w}_1}{\overset{\mathbf{d}_0 + a_1}{\mathbf{G}}} = M_1, \text{ as } t \circledast \not\equiv 1
$$

so, $x_1(t)$,, M_1 . From Eq.(2), we have

$$
\frac{dx_2(t)}{dt} = \frac{a_3x_1(t)}{1 + a_4x_3(t)} - w_2x_2(t),
$$

., $a_3M_1 - w_2x_2(t)$,

Which gives $x_2(t)$,, $(a_3M_1/w_2) = M_2$, as $t \otimes \Psi$. Finally, in Eq. (3) , it obtains

$$
\frac{dx_3(t)}{dt} = a_5(x_2(t)^2) - w_3x_3(t),
$$

., $a_5M_2^2 - w_3x_3(t)$.

Hence $x_3(t)$,, $(a_5M_2^2/w_3) = M_3$ as $t \otimes \Psi$.

The proof is complete. W

III. EXISTENCE OF EQUILIBRIUMS

From Eqs. $(1)-(3)$, the system of algebraic equations as

$$
a_0 + C \frac{a_1}{\left(1 + a_2(x_3^*)^2\right)} \frac{x_1}{(m + x_1^*)} - w_1 x_1^* = 0,
$$

$$
\frac{a_3 x_1^*}{1 + a_4 x_3^*} - w_2 x_2^* = 0,
$$
 (4)

$$
a_5(x_2^*)^2 - w_3 x_3^* = 0,
$$

can provide the first equilibrium point $E_0(0,0,0)$, $(a_0 = 0)$ and the second equilibrium point $(a_0^{-1} \ 0)$, $E_1(x_1^*, x_2^*, x_3^*)$, where $x_3^* = (a_5(x_2^*)^2 / w_3) > 0$, the values of $x_1^*, x_2^* > 0$ are in the system of equations,

$$
A_1 x_1^* + (B_1 + C_1 (x_2^*)^2) x_2^* = 0,
$$

$$
A_2 x_1^* + (B_2 x_1^* + C_2 x_1^* + D_2) (x_2^*)^4 = E_2,
$$
 (5)

where the constants are

$$
A_1 = a_3 w_3, \t B_1 = w_2 w_3,
$$

\n
$$
C_1 = a_4 a_5 w_2 (x_2^*)^2,
$$

\n
$$
A_2 = C a_1 w_3^2 - m w_1 w_3^2 - w_1 w_3^2 x_1^* + a_0 w_3^2,
$$

\n
$$
B_2 = - a_2 a_5^2 w_1, \t C_2 = a_0 a_2 a_5^2 - m a_2 a_5^2 w_1,
$$

\n
$$
D_2 = m a_0 a_2 a_5^2, \t E_2 = -m a_0 w_3^2.
$$

The Newton-Raphson method [7] can be applied to solve $x_2^*, x_3^*.$

IV. THE BASIC REPRODUCTION NUMBER

A basic reproductive number (R_0) is the average ratio number for the current levels of hormones as the first stage and the level of the hormone at the next time as second stage, which is widely used to analyse whether increasing or decreasing levels of hormones [8]. We apply the nextgeneration method [9] to compute a basic reproductive number (R_0) by compartment the HPA axis model as

$$
F = \begin{matrix} \n\dot{\xi} & Ca_1x_1 & \dot{\psi} & \dot{\xi} & w_1x_1 - a_0 & \dot{\psi} \\ \n\dot{\theta}(a_2x_3^2 + 1)(m + x_1) & \dot{\psi} & \dot{\xi} & w_1x_1 - a_0 & \dot{\psi} \\ \n\dot{\theta} & \dot{\theta} & \dot{\psi} & \dot{\xi} & a_3x_1 & \dot{\psi} \\ \n\dot{\xi} & \dot{\theta} & \dot{\xi} & a_4x_3 + 1 & w_2x_2\dot{\psi} & \dot{\psi} \\ \n\dot{\xi} & 0 & \dot{\psi} & \dot{\xi} & - a_5x_2^2 + w_3x_3 & \dot{\psi} \\ \n\dot{\xi} & 0 & \dot{\psi} & \dot{\xi} & - a_5x_2^2 + w_3x_3 & \dot{\psi} \n\end{matrix}
$$

Two Jacobian matrices of F and V at $E_0(0,0,0)$ can provide the next generation matrix as

$$
FV^{-1} = \begin{matrix} \frac{6}{6}Ca_1/mw_1 & 0 & 0\\ \frac{6}{6} & 0 & 0 & 0\\ \frac{6}{6} & 0 & 0 & 0 \end{matrix}
$$

where all eigenvalues of FV^{-1} are $l_1 = Ca_1/mv_1$, $l_{2,3} = 0$. Consequently, the basic reproduction number (R_0) is

$$
R_0 = \frac{Ca_1}{mw_1}, \text{ where } a_0 = 0. \tag{6}
$$

If $R_0 < 1$, i.e. $Ca_1 < m w_1$ then the hormone cortisol will gradually decrease to 0, which means that the depression is slowing down. On the other hand, if $R_0 > 1$ cause more depression which affects to a patient.

V. THE LOCAL STABILITY OF THE HPA AXIS MODEL The stability is a way of determining behaviour for three hormones and some sufficient conditions of local stability.

Lemma 3 The hormone-free equilibrium $E_0(0,0,0)$ of HPA axis model Eqs. (1)-(3) is locally asymptotically stable if $R_0 < 1$ and unstable if $R_0 > 1$.

Proof: The Jacobian matrix of Eqs. (1)-(3) at $E_0(0,0,0)$ is obtained by

$$
J(E_0) = \begin{cases} \frac{\mathfrak{F}}{\mathfrak{S}} C a_1 / m w_1 \mathfrak{f} & 0 & 0 \text{ u} \\ \frac{\mathfrak{S}}{\mathfrak{S}} & a_3 & -w_2 & 0 \text{ u} \\ \frac{\mathfrak{S}}{\mathfrak{S}} & 0 & 0 & -w_3 \text{ u} \end{cases}
$$

where the characteristic equation is

$$
(l + w_3)(l + w_2)(l - \frac{a_1C}{m} + w_1) = 0.
$$

The necessary condition for local stability is the real parts of all eigenvalues must be negative. It is obvious that $l_1 = -w_3 < 0, l_2 = -w_2 < 0$ and

$$
l_3 = \frac{Ca_1 - mw_1}{m} = w_1(R_0 - 1) < 0, R_0 < 1.
$$

So, the hormone-free equilibrium $E_0(0,0,0)$ is locally asymptotically stable if $R_0 < 1$ and unstable if $R_0 > 1$. W **Lemma 4**The equilibrium $E_1(x_1^*, x_2^*, x_3^*)$, $x_i^* \dots 0$, $i = 1, 2, 3$ in (1)-(3) is locally asymptotically stable, when $d_1d_2 > d_3$ which is sufficient conditions of the Routh-Hurwitz criterion [10].

Proof: The Jacobian matrix of the model at E_1 is

$$
J(E_1) = \begin{cases} \n\dot{\xi} & D & 0 & -2Aa_2x_1^*x_3^*(m + x_1^*)\dot{\mathbf{u}}_1^* \\
J(E_1) = \begin{cases} \n\dot{\xi} & 0 & -N_2 \\
\dot{\xi} & 0 & 2a_5x_2^* & -N_3 & \dot{\mathbf{u}}_1^* \\
\dot{\xi} & 0 & 2a_5x_2^* & -N_3 & \dot{\mathbf{u}}_2^* \\
\dot{\xi} & 0 & -N_3 & \dot{\mathbf{u}}_3^* \\
\dot{\xi} & 0 & -N_3 & \dot{\mathbf{u}}_4^* \\
\dot{\xi} & 0 & -N_3 & \dot{\mathbf{u}}_5^* \\
\dot{\xi} & 0 & -N_3 & \dot{\mathbf{u}}_6^* \\
\dot{\xi} & 0 & -N_3 & \dot{\mathbf{u}}_7^* \\
\dot{\xi} & 0 & -N_3 & \dot{\mathbf{u}}_8^* \\
\dot{\xi} & 0 & -N_3 & \dot{\mathbf{u}}_9^* \\
\dot{\xi} &
$$

so the characteristic equation becomes

$$
l^3 + d_1l^2 + d_2l + d_3 = 0,
$$

and all coefficients are

$$
d_{1} = w_{1} + w_{2} + w_{3} - \frac{a_{1}Cm}{(a_{2}(x_{3}^{*})2 + 1)(m + x_{1}^{*})^{2}} > 0,
$$
\n
$$
d_{2} = \frac{2a_{3}a_{4}a_{5}x_{1}^{*}x_{2}^{*}}{(a_{4}x_{3}^{*} + 1)^{2}} + w_{1}(w_{2} + w_{3}) + w_{2}w_{3}
$$
\n
$$
- \frac{a_{1}Cm(w_{2} + w_{3})}{(a_{2}x_{3}^{*2} + 1)(m + x_{1}^{*})^{2}} > 0,
$$
\n
$$
d_{3} = \frac{2Ca_{1}a_{2}a_{3}a_{5}x_{1}^{*}x_{2}^{*}x_{3}^{*}(ma_{4}x_{3}^{*} + 2a_{4}x_{1}^{*}x_{3}^{*} + 2m)}{(a_{4}x_{3}^{*} + 1)^{2}(a_{2}x_{3}^{*2} + 1)^{2}(m + x_{1}^{*})^{2}} + \frac{2Ca_{1}a_{3}a_{5}x_{1}^{*}x_{2}^{*}(2a_{2}x_{1}^{*}x_{3}^{*} - ma_{4})}{(a_{4}x_{3}^{*} + 1)^{2}(a_{2}(x_{3}^{*})^{2} + 1)^{2}(m + x_{1}^{*})^{2}} + w_{1}w_{2}w_{3} + \frac{2a_{3}a_{4}a_{5}w_{1}x_{1}^{*}x_{2}^{*}}{(a_{4}x_{3}^{*} + 1)^{2}} - \frac{Cma_{1}w_{2}w_{3}}{(a_{4}x_{3}^{*} + 1)^{2}} - \frac{Cma_{1}w_{2}w_{3}}{(a_{4}x_{3}^{*} + 1)^{2}} - \frac{Cma_{1}w_{2}w_{3}}{(a_{4}x_{3}^{*} + 1)^{2}} - \frac{Cma_{1}w_{2}w_{3}}{(a_{4}x_{3}^{*} + 1)^{2}} + \frac{C^{2}m^{2}a_{1}^{2}(w_{2} + w_{3}) + w_{2}^{2}(w_{1} + w_{2}) + w_{3}^{2}(w_{1} + w_{2}) + w_{3}w_{2}w_{3} + \frac{2a_{3}a_{4
$$

Since $d_1 > 0, d_3 > 0$, if $d_1d_2 - d_3 > 0$ which satisfies the

 $E_1(x_1^*, x_2^*, x_3^*)$ criterion. Routh-Hurwitz then is asymptotically stable. W

In numerical simulation for the HPA axis model, the parameter values are given in Table 2.

Table-II: The parameter values of depression model [6]

Parameters	Meaning	Unit
\boldsymbol{m}	$5.8300'$ 10^2	pg/mL
a_0	3.9031' 10 ^{4}	pg/(mL ×min)
a_{1}	6.8390' 10^{12}	$pg/(mL \times min)$
a ₂	$1.7809'$ 10^9	$(dL/mg)^2$
a_{3}	$2.2803'$ 10^4	\min^{-1}
$a_{\scriptscriptstyle{A}}$	$1.7745'$ 10^5	dL/mg
a_{ς}	4.6170' 10 ⁻⁴	mg/dL
		$min(pg/mL)^2$
W_1	0.0337	min^{-1}
W_2	0.0205	min^{-1}
W_3	0.0238	min^{-1}
C	0.07978	

The numerical results and all parameters in Table 2, the equilibrium $E_1(8.895, 14.218, 3.922)$ is local stability by Lemma 4 where the values of $d_1 = 0.045 > 0$, $d_2 = 0.001 > 0$ and $d_1 d_2$ - $d_3 = 2.507'$ 10⁻⁷ > 0. The graphs of solutions are depicted for determining the local stability for $0, t, 14400$ (mins) as shown in the following graphs.

Fig. 2: Graph of local stability for the depression model.

VI. SENSITIVITY ANALYSIS OF THE EQUILIBRIUM POINT

A sensitivity analysis is the study of how changing values of parameter that effect to some levels of hormones in the HPA axis model. The sensitivity index can determine the most effective parameters for changing levels of a hormone. $x_i^* \hat{1} \{x_1^*, x_2^*, x_3^* \}$ and

$$
k_j \hat{1} \{a_0, a_1, a_2, a_3, a_4, a_5, m, w_1, w_2, w_3\}, j = 1, 2, 4, 10.
$$

The sensitivity index [6] of x_i^* with respect to parameters k_j is defined by

is defined by
\n
$$
SI(x_i^*, k_j) = \frac{k_j \mathbf{g} \cdot \mathbf{g} \cdot \mathbf{g}}{x_i^* \mathbf{g} \cdot \mathbf{g} \cdot \mathbf{g}} i = 1, 2, 3, j = 1, 2, 3, 4, 10.
$$

Taking partial derivative for each x_i^* , $i = 1,2,3$ in the

system (4) with respect to the parameter
$$
a_0
$$
, it obtains
\n
$$
\frac{\sqrt{2}}{\sqrt{2}} \left(\frac{a_0}{a_0} + C \frac{a_1}{(1 + a_2(x_3^*)^2)} \frac{x_1^*}{(m + x_1^*)} - w_1 x_1^* \frac{\frac{a_1^*}{a_1^*}}{\frac{a_2^*}{b_0^*}} - 1 \right)
$$
\n
$$
\frac{a_3}{1 + a_4 x_1^*} \frac{\sqrt{a_1 x_1^*}}{\sqrt{a_1 x_2^*}} - w_2 \frac{\sqrt{a_1 x_2^*}}{\sqrt{a_1 x_2^*}} \frac{a_3 a_4 x_1^*}{(1 + a_4 x_1^*)^2} \frac{\sqrt{a_1 x_3^*}}{\sqrt{a_1 x_2^*}} \frac{a_1^*}{\sqrt{a_0 x_2^*}} - 0,
$$
\n
$$
2a_5 x_2^* \frac{\sqrt{a_1 x_2^*}}{\sqrt{a_1 x_2^*}} \frac{a_1^*}{\sqrt{a_2 x_2^*}} \frac{\sqrt{a_1 x_3^*}}{\sqrt{a_1 x_2^*}} \frac{a_2^*}{\sqrt{a_1 x_2^*}} = 0,
$$

it obtains the matrix equation

* 1 *x* é ù ¶ ê ú ê ú ¶ 0 1 * * * ² 4 3 2 4 1 * 0 5 2 3 * 3 0 0 1 (1) 0 . 0 2 0 *a D E x B a x Ba x a a x x a w w w* é ù é ù ê ú - - ê ú ê ú ê ú ê ú ¶ ê ú ê ú + - - = ê ú ê ú ê ú ê ú ¶ ê ú ê ú ë û ë û - ê ú ê ú ¶ ê ú ê ú ¶ ë û

where

$$
A = \frac{a_1 C}{(a_2(x_3^*)^2 + 1)^2 (m + x_1^*)^2}, B = \frac{a_3}{(a_4 x_3^* + 1)^2},
$$

\n
$$
D = A(a_2(x_3^*)^2 + 1)(m + x_1^*) - Ax_1^*(a_2(x_3^*)^2 + 1),
$$

\n
$$
E = -2Aa_2x_1^*x_3^*(m + x_1^*).
$$

The partial derivatives $\P_{x_i}^*$ $\int x_i^* / \int a_0, i = 1, 2, 3$ can be solve,

$$
i = 3, \text{ for example the sensitivity index is}
$$
\n
$$
SI(x_3^*, a_0) = \frac{a_0}{x_3^*} \frac{\frac{30}{x_3} \frac{1}{x_3^*}}{\frac{30}{x_3^*}} = \frac{2Ba_0w_3^2 \left(a_4a_5(x_2^*)^2 + w_3\right)}{M},
$$

where

$$
M = \left(2ABa_2a_4a_5^3x_1^*(x_2^*)^5(m+2x_1^*)-\nAa_2a_5^2w_3(x_2^*)^3\left(mw_2x_2^* - 4Bx_1^*(m+x_1^*)\right)\n- w_3^2(Am-w_1)(2Ba_4a_5x_1^*x_2^* + w_2w_3)\right)x_2^*.
$$

The sensitivity index of x_1^*, x_2^* and x_3^* for each parameter can be shown in Table 2 with the parameters in Table 3.

Table-III:Sensitivity indices for the equilibrium point

Parameters	* x_1	\ast x_2	x_{3}
\boldsymbol{m}	0.00097	0.00032	0.00064
a_0	0.74092(3)	0.24697	0.49395(2)
a_{1}	$-0.74092(3)$	-0.24697	$-0.49395(2)$
a ₂	$-0.98790(1)$	0.00403	0.00807
a_{3}	0.98790(1)	-0.00403	-0.00807
$a_{\scriptscriptstyle{A}}$	-0.49395	-0.49798	0.00403
a_{ς}	$-0.72979(4)$	-0.24326	$-0.48653(3)$
W_1	$-0.74189(2)$	-0.24730	$-0.49459(1)$
W_2	0.98790(1)	-0.00403	-0.00807
W_3	0.49395	0.49798	-0.00403

Table 3 shows that the parameters a_3 , a_4 , and w_2 are the most effective parameters to hormone x_1 . For example, if a_4 and w_2 decrease or a_3 increases, then the hormone levels of x_1 decreases rapidly. In the other hand, decreasing hormone cortisol x_3 we have to increasing w_1 , a_2 and deceasing a_1 for reducing hormone cortisol.

VII. GLOBAL ATTRACTIVITY OF THE HPA AXIS MODEL Too much stress that affects from high levels of hormone cortisol may cause abnormally high levels of risk for depression. In this section, we extend the HPA axis model by including impulsive condition in order to controlling

$$
\frac{dx_1}{dt} = a_0 + C \frac{a_1}{(1 + a_2 x_3^2)} \frac{x_1}{(m + x_1)} - w_1 x_1 \frac{\ddot{\mathbf{i}}}{t}
$$
\n
$$
\frac{dx_2}{dt} = \frac{a_3 x_1}{1 + a_4 x_3} - w_2 x_2,
$$
\n
$$
\frac{dx_3}{dt} = a_5 x_2^2 - w_3 x_3,
$$
\n
$$
x_1(t^+) = x_1(t),
$$
\n
$$
x_2(t^+) = x_2(t),
$$
\n
$$
\frac{dx_3}{dt} = \frac{a_3 x_1}{1 + a_4 x_3} - \frac{a_3 x_2}{1 + a_5 x_2} - \frac{a_3 x_3}{1 + a_6 x_3}
$$
\n(7)

In addition, $x_1(t^+), x_2(t^+)$ and $x_3(t^+)$ represent the levels of hormones CRH, ACTH and cortisol after the n^{th} pulse. We determine the amount of medication dispensed to

patients $q \in [0,1)$ at each moment of pulsing time nT , where $n = 1, 2, \dots$, and T is the period of impulsive effect, into the HPA axis model. Here, some definitions, notations are useful for our main results.

Definition 1*(Dini derivative [11])*

The right upper Dini derivative $D^+f(t)$ *of a continuous function* $f: \Box \rightarrow \Box$ *at t is*

$$
D^+ f(t) = \limsup_{h \to 0^+} \frac{f(t+h) - f(t)}{h}.
$$

If f is differentiable at t , then $D^+ f(t) = df(t) / dt$, where $df(t)/dt$ is the usual derivative at t .

Definition 2*A model is said to be globally attractive [12], if for any two solutions* $x_1(t)$ *and* $x_2(t)$ *, then*

$$
\lim_{t \to \infty} |x_1(t) - x_2(t)| = 0.
$$

Lemma 5*(Barbalat's lemma [13]) Let f be a nonnegative function defined on* $[0, \infty)$ *such that f is* \int *integrable on* $[0, \infty)$ *and uniformly continuous on* $[0, \infty)$, *then* $\lim_{t\to\infty} f(t) = 0$.

Theorem 1*Suppose that there exist constants*

$$
\mu_{i} > 0, i = 1, 2, 3 \text{ such that } A_{j} > 0, j = 0, 1, 2 \text{ where}
$$
\n
$$
A_{0} = \mu_{i} \text{sign}\left(x_{1}^{(1)}(t) - x_{1}^{(2)}(t)\right) \left\{a_{i}CM_{1} - \left(\frac{1}{(1 + a_{2}M_{3}^{2})(\mu + M_{1})} - \frac{1}{(\mu + m_{1})}\right)\right\}
$$
\n
$$
+ \mu_{2} \text{sign}\left(x_{2}^{(1)}(t) - x_{2}^{(2)}(t)\right) \left\{a_{3}M_{1}n\right\}
$$
\n
$$
\cdot \left(\frac{1}{1 + a_{4}M_{3}} - \frac{1}{1 + a_{4}m_{3}}\right)\right\},
$$
\n
$$
A_{1} = \mu_{1}\omega_{1} - \frac{\mu_{1}a_{1}C}{(1 + a_{2}m_{3}^{2})(\mu + m_{1})} - \frac{\mu_{2}a_{3}}{1 + a_{4}m_{3}},
$$
\n
$$
A_{2} = \mu_{2}\omega_{2} - 2\mu_{3}a_{5}M_{2},
$$
\n(8)

where M_1 , M_2 and M_3 are given in Lemma 2. Then *solution of Eqs. (1)-(3)is globally attractive.*

Proof: Let
$$
(x_1^{(1)}(t), x_2^{(1)}(t), x_3^{(1)}(t))
$$
 and

 $(x_1^{(2)}(t), x_2^{(2)}(t), x_3^{(2)}(t))$ be any solutions of the HPA axis model in Eqs. (1)-(3). From Lemma 2, without loss of generality, we may assume that

enerality, we may assume that
 $m_1, x_1^{(k)}(t), M_1, m_2, x_2^{(k)}(t), M_2, m_3, x_3^{(k)}(t), M_3,$

for all $t \cdot .0$ and $k = 1, 2$. We define a function is $V_1(t) = \mu_1 \left| x_1^{(1)}(t) - x_1^{(2)}(t) \right|$ then the right upper Dini derivative of $V_1(t)$ along Eq. (1) is given by

$$
D^{\dagger}V_{1}(t) = D^{\dagger} \mu_{1} |x_{1}^{(1)}(t) - x_{1}^{(2)}(t)|,
$$
\n
$$
= \mu_{1} \text{sign}(\mathbf{x}_{1}^{(1)}(t) - \mathbf{x}_{1}^{(2)}(t)) \{D^{\dagger} x_{1}^{(1)}(t) - D^{\dagger} x_{1}^{(2)}(t)\},
$$
\n
$$
= \mu_{1} \text{sign}(\mathbf{x}_{1}^{(1)}(t) - \mathbf{x}_{1}^{(2)}(t))
$$
\n
$$
\begin{cases}\n a_{1}C \cdot \left[\frac{x_{1}^{(1)}(t)}{\left(1 + a_{2}(\mathbf{x}_{3}^{(2)}(t))^{2}\right) \left(\mu + \mathbf{x}_{1}^{(1)}(t)\right)} - \frac{x_{1}^{(2)}(t)}{\left(1 + a_{2}(\mathbf{x}_{3}^{(2)}(t))^{2}\right) \left(\mu + \mathbf{x}_{1}^{(2)}(t)\right)}\right] \\
-a_{1}(\mathbf{x}_{1}^{(1)}(t) - \mathbf{x}_{1}^{(2)}(t))\right],
$$
\n
$$
a_{1} \text{sign}(\mathbf{x}_{1}^{(1)}(t) - \mathbf{x}_{1}^{(2)}(t))\},
$$
\n
$$
a_{1}C \cdot \left(\frac{x_{1}^{(1)}(t)}{(\mu + m_{1})} - \frac{x_{1}^{(2)}(t)}{(1 + a_{2}M_{3}^{2})(\mu + M_{1})}\right) \\
-a_{1}(\mathbf{x}_{1}^{(1)}(t) - \mathbf{x}_{1}^{(2)}(t))\},
$$
\n
$$
= \mu_{1} \text{sign}(\mathbf{x}_{1}^{(1)}(t) - \mathbf{x}_{1}^{(2)}(t))\}
$$
\n
$$
+ \frac{x_{1}^{(2)}(t)}{(\mu + m_{1})} - \frac{x_{1}^{(2)}(t)}{(1 + a_{2}M_{3}^{2})(\mu + M_{1})}\
$$
\n
$$
-a_{1}(\mathbf{x}_{1}^{(1)}(t) - \mathbf{x}_{1}^{(2)}(t))\}
$$
\n
$$
a_{1} \text{sign}(\mathbf{x}_{1}^{(1)}(t) - \mathbf{x}_{1}^{(2)}(t))\}
$$
\n

Define $V_2(t) = \mu_2 | x_2^{(1)}(t) - x_2^{(2)}(t) |$. The right upper Dini derivative along Eq. (2), we have

$$
D^{+}V_{2}(t) = \mu_{2}sign\left(x_{2}^{(1)}(t) - x_{2}^{(2)}(t)\right)
$$
\n
$$
\begin{cases}\na_{3}(\frac{x_{1}^{(1)}(t)}{1 + a_{4}m_{3}} - \frac{x_{1}^{(2)}(t)}{1 + a_{4}m_{3}} + \frac{x_{1}^{(2)}(t)}{1 + a_{4}m_{3}} - \frac{x_{1}^{(2)}(t)}{1 + a_{4}M_{3}}\right) \\
-\omega_{2}\left(x_{2}^{(1)}(t) - x_{2}^{(2)}(t)\right), \\
\vdots \\
\omega_{3}sign\left(x_{2}^{(1)}(t) - x_{2}^{(2)}(t)\right) \\
\vdots \\
\frac{a_{3}}{1 + a_{4}m_{3}}\left(x_{1}^{(1)}(t) - x_{1}^{(2)}(t)\right) \\
+ a_{3}M_{1}\left(\frac{1}{1 + a_{4}m_{3}} - \frac{1}{1 + a_{4}M_{3}}\right) \\
-\omega_{2}\left(x_{2}^{(1)}(t) - x_{2}^{(2)}(t)\right), \\
\vdots \\
\omega_{4}sign\left(x_{1}^{(1)}(t) - x_{2}^{(2)}(t)\right)\n\end{cases}
$$
\n
$$
\begin{cases}\na_{3}M_{1}\left(\frac{1}{1 + a_{4}m_{3}} - \frac{1}{1 + a_{4}M_{3}}\right) \\
-\frac{1}{1 + a_{4}M_{3}}\n\end{cases}
$$
\n
$$
- \frac{1}{1 + a_{4}M_{3}}\n\begin{cases}\n\frac{a_{3}}{1 + a_{4}m_{3}} |x_{1}^{(1)}(t) - x_{1}^{(2)}(t)| \\
-\omega_{2} |x_{2}^{(1)}(t) - x_{2}^{(2)}(t)|\n\end{cases}
$$

Finally define $V_3(t) = \mu_3 |x_3^{(1)}(t) - x_3^{(2)}(t)|$. Then the Dini

derivative of
$$
V_3
$$
 is
\n
$$
D^+V_3(t) = \mu_3 \text{sign}\left(x_3^{(1)}(t) - x_3^{(2)}(t)\right) \left\{ a_5 \left(x_2^{(1)}(t)\right)^2 - \left(x_2^{(2)}(t)\right)^2 -\omega_3 \left(x_3^{(1)}(t) - x_3^{(2)}(t)\right) \right\},
$$
\n
$$
= \mu_3 \text{sign}(x_3^{(1)}(t) - x_3^{(2)}(t)) \left\{ a_5 \left(x_2^{(1)}(t) - x_2^{(2)}(t)\right) - \left(x_2^{(1)}(t) + x_2^{(2)}(t)\right) - \omega_3 \left(x_3^{(1)}(t) - x_3^{(2)}(t)\right) \right\},
$$
\n
$$
\dots \mu_3 \text{sign}\left(x_3^{(1)}(t) - x_3^{(2)}(t)\right) \left\{ 2a_5 M_2 \left(x_2^{(1)}(t) + x_2^{(2)}(t)\right) - \omega_3 \left(x_3^{(1)}(t) - x_3^{(2)}(t)\right) \right\},
$$
\n
$$
\dots \mu_3 \left\{ 2a_5 M_2 \left| x_2^{(1)}(t) - x_2^{(2)}(t) \right| - \omega_3 \left| x_3^{(1)}(t) - x_3^{(2)}(t) \right| \right\}.
$$
\nDefine the Lyapunov function $V(t) = V_1(t) + V_2(t) + V_3(t)$, it

obtains

$$
D^{\dagger}V(t), -\left[\mu_{1}\text{sign}\left(x_{1}^{(1)}(t) - x_{1}^{(2)}(t)\right)\left\{a_{1}CM_{1} \right.\n\cdot \left(\frac{1}{(1 + a_{2}M_{3}^{2})(\mu + M_{1})} - \frac{1}{(\mu + m_{1})}\right)\right\} + \mu_{2}\text{sign}\left(x_{2}^{(1)}(t) - x_{2}^{(2)}(t)\right)\left\{a_{3}M_{1} \right.\n\cdot \left(\frac{1}{1 + a_{4}M_{3}} - \frac{1}{1 + a_{4}m_{3}}\right)\right] -\left(\mu_{1}\omega_{1} - \frac{\mu_{1}a_{1}C}{(\mu + m_{1})} - \frac{\mu_{2}a_{3}}{1 + a_{4}m_{3}}\right)\left|x_{1}^{(1)}(t) - x_{1}^{(2)}(t)\right| - (\mu_{2}\omega_{2} - 2\mu_{3}a_{5}M_{2})\left|x_{2}^{(1)}(t) - x_{2}^{(2)}(t)\right| - (\mu_{3}\omega_{3})\left|x_{3}^{(1)}(t) - x_{3}^{(2)}(t)\right|,
$$
\n
$$
= -\left(A_{0} + A_{1}\left|x_{1}^{(1)}(t) - x_{1}^{(2)}(t)\right| + A_{3}\left|x_{3}^{(1)}(t) - x_{3}^{(2)}(t)\right|).
$$
\n
$$
t = \mathbf{r} \mathbf{T} \mathbf{r} = 1.2 \qquad \text{we see obtain that}
$$

For
$$
t = nT
$$
, $n = 1, 2, ...$, we can obtain that
\n
$$
V(t^+) = V_1(t^+) + V_2(t^+) + V_3(t^+)
$$
\n
$$
= \mu_1 |x_1^{(1)}(t^+) - x_1^{(2)}(t^+)| + \mu_2 |x_2^{(1)}(t^+) - x_2^{(2)}(t^+)|
$$
\n
$$
+ \mu_3 |x_3^{(1)}(t) - x_3^{(2)}(t)|,
$$
\n
$$
= \mu_1 |x_1^{(1)}(t^+) - x_1^{(2)}(t^+)| + \mu_2 |x_2^{(1)}(t^+) - x_2^{(2)}(t^+)|
$$
\n
$$
+ \mu_3 |(1-q)x_3^{(1)}(t) - (1-q)x_3^{(2)}(t)|,
$$
\n
$$
= \mu_1 |x_1^{(1)}(t^+) - x_1^{(2)}(t^+)| + \mu_2 |x_2^{(1)}(t^+) - x_2^{(2)}(t^+)|
$$
\n
$$
+ (1-q)\mu_3 |x_3^{(1)}(t) - x_3^{(2)}(t)|,
$$
\n
$$
= V_1(t) + V_2(t) + (1-q)V_3(t) = V(t).
$$

Since A_j , $j = 0, 1, 2$ are defined in Eq.(8) and $A_3 = \mu_3 \omega_3 > 0$. Then we select $\xi > 0$ such that $\xi = min{ A_0, A_1, A_2 }$. In consequence, we obtain for all t ... T_0

$$
t_{\cdot} \cdot T_0
$$

\n
$$
D^+ V(t), -\xi \left(1 + \left|x_1^{(1)}(t) - x_1^{(2)}(t)\right| + \left|x_2^{(1)}(t) - x_2^{(2)}(t)\right| + \left|x_3^{(1)}(t) - x_3^{(2)}(t)\right|\right),
$$

\n
$$
+ \left|x_3^{(1)}(t) - x_3^{(2)}(t)\right|,
$$

\n
$$
+ \xi z(t),
$$

\n(9)

where

where
\n
$$
z(t) = |x_1^{(1)}(t) - x_1^{(2)}(t)| + |x_2^{(1)}(t) - x_2^{(2)}(t)| + |x_3^{(1)}(t) - x_3^{(2)}(t)|,
$$
\nso $D^+V(t)$,, $-\xi z(t)$,, N , $N > 0$.
\nConsider $\mu = \min{\{\mu_1, \mu_2, \mu_3\}}$ in Eq. (9), then
\n
$$
\mu z(t)
$$
,, $\mu_1 |x_1^{(1)}(t) - x_1^{(2)}(t)| + \mu_2 |x_2^{(1)}(t) - x_2^{(2)}(t)| + \mu_3 |x_3^{(1)}(t) - x_3^{(2)}(t)|,$ \n
$$
= V(t),
$$
\n(10)

taking the right upper Dini derivative along Eq.(10), we have $\mu D^{\dagger} z(t), D^{\dagger} V(t), N$, thus $D^{\dagger} z(t), (N/\mu) = M$,

and $D^+z(t)$ is bounded. Integrating Eq. (9)from T_0 to *t* , then we have

$$
V(t) + \xi \int_{T_0}^t z(s) ds \, , \, V(T_0),
$$

which gives

ch gives
\n
$$
\xi \int_{T_0}^{t} z(s) ds, \ V(t) + \xi \int_{T_0}^{t} z(s) ds, \ V(T_0), \ V(t) > 0.
$$

Hence,

$$
\xi \int_{T_0}^{t} z(s)ds < \infty \text{ or } \int_{T_0}^{t} z(s)ds < \infty.
$$
 (11)

So, $z(t)$ is integrableon $[0, \infty)$. Since $A_j > 0$, $j = 0, 1, 2, 3$ and the solutions $(x_1^{(1)}(t), x_2^{(1)}(t), x_3^{(1)}(t))$ and $\left(x_1^{(2)}(t), x_2^{(2)}(t), x_3^{(2)}(t)\right)$ on $[0, \infty)$ are bounded by Lemma 2. So, $|x_1^{(1)}(t) - x_1^{(2)}(t)|$, $|x_2^{(1)}(t) - x_2^{(2)}(t)|$ and $x_3^{(1)}(t) - x_3^{(2)}(t)$ are bounded and uniformly continuous $[14]$ on $[0, \infty)$. By Lemma 5, then

$$
\lim_{t \to \infty} \left| x_1^{(1)}(t) - x_1^{(2)}(t) \right| = 0,
$$

\n
$$
\lim_{t \to \infty} \left| x_2^{(1)}(t) - x_2^{(2)}(t) \right| = 0,
$$

\n
$$
\lim_{t \to \infty} \left| x_3^{(1)}(t) - x_3^{(2)}(t) \right| = 0.
$$

Therefore, all solution are globally attractive. W

The following graphs show the levels of three hormones (x_1, x_2, x_3) with two initial conditions $(2,18,10)$, (60,30,18) respectively in 5000 minutes.

Fig. 3. Graphs of hormones x_1, x_2 and x_3 respectively

Fig. 4. Phase planes of hormones (x_1, x_2) , (x_1, x_3) and

Fig. 5. Graph 3-D of all three hormones

Finally, we compare numerical results of the model between without impulse and impulse behavior, where $q = 0.01$ and $T = 1$ for $t \in [0, 5000]$ with the initial condition (20,18,2) by using the parameter values in Table 2.

Fig. 6. Graphs of hormones x_1, x_2 and x_3 respectively

Fig. 7. Phase planes of hormones (x_1, x_2) , (x_1, x_3) and

(x_{1}, x_{2})

VIII. CONCLUSION

In this work, we studied the mathematical HPA axis model with/without impulse condition and further analyzed it in the case of the HPA axis model in order to be able to interpret system behavior over a longer period of time. For sensitivity analysis of the equilibrium point, we are able to determine which parameters are the most affect to hormonal changes in the system. Finally, we investigate conditions for global attractivity for impulsive behavior of the HPA axis model. The results of sensitivity analysis and global attractivity in the HPA axis model can be used for treatment and medication to patients precisely.

IX. ACKNOWLEDGMENT

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